

Bachelor/Master Seminar

Embedded Systems and Robotics (WS 2018/19)

Date/place	Time	Name	Discipline	Topic
06/02/2019 Room: 48-365	08:30-09:05	Tobias Decker	Bachelor (CS)	Monokamera-Radar-Fusionsansätze für SLAM
	09:05-09:40	Katharina Roth	Bachelor (CS)	Filter Techniques for Radar Sensors in Autonomous Driving
	Break			
	09:50-10:35	Niklas Klipphahn	Master (CS)	Pedestrian Path Prediction for Autonomous Vehicles
	10:35-11:20	Alruba Khan	Master (CS)	Reinforcement Learning in Autonomous Vehicles
	11:20-12:05	Hagen Herrmann	Master (CS)	Sensor-based Technology for Safety in Construction Site
	Lunch Break			
	13:00-13:45	Yannic Bonenberger	Master (CS)	FPGAs for EKF and SLAM
	13:45-14:30	Max Stein	Master (CS)	Feature Visualization in CNNs
	Break			
	14:45-15:30	Michael Wittemaier	Master (CS)	State-of-the-art in Point Set Registration Algorithms
	15:30-16:15	Qazi Hamza Jan	PhD Candidate	Autonomous Navigation through Pedestrian Path with Pedestrian Tracking